L Number	Hits	Search Text	DB	Time stamp
-	2	"20040010386"	USPAT;	2004/09/30 10:51
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	2	6683774.pn.	USPAT;	2004/08/27 11:05
		•	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	35652	rotational and angle and detection	USPAT;	2004/08/27 11:05
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	702	(rotational and angle and detection) and resolver	USPAT;	2004/08/27 11:05
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	2857	(rotational and angle and detection) and offset and gain	USPAT;	2004/08/27 11:05
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
	400	// -1-1111111	IBM_TDB	2004/00/27 46.42
-	133	((rotational and angle and detection) and resolver) and	USPAT;	2004/08/27 16:42
		((rotational and angle and detection) and offset and gain)	US-PGPUB;	
			EPO; JPO;	
			DERWENT; IBM_TDB	
	4	(rotational near angle near detection) and offset and gain	USPAT;	2004/08/27 12:06
-	7	and maximum and minimum	US-PGPUB;	2004/00/27 12.00
		and maximum and minimum	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
_	350	resolver and offset and gain and maximum and minimum	USPAT;	2004/09/17 12:49
		<b>3</b>	US-PGPUB;	' '
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	1	(correcting near resolver near output).ti.	USPAT;	2004/08/27 12:56
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	1	correcting near resolver near output	USPAT;	2004/08/27 12:56
			US-PGPUB;	
			EPO; JPO;	]
		•	DERWENT;	
			IBM_TDB	2004/09/27 42:56
-	686	correcting and resolver and output	USPAT;	2004/08/27 12:56
			US-PGPUB;	
			EPO; JPO;	
			DERWENT; IBM_TDB	
	175	(correcting and resolver and output) and offset and gain	USPAT;	2004/08/27 14:16
-	1/3	(correcting and resolver and output) and onset and gain	US-PGPUB;	2007/00/27 14.10
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
L	L	1	,, - ,	1

		r	11100 477	T 000 4/00 /00 4 4 4 4
-	3934	rotational same angle same detection	USPAT;	2004/08/27 14:17
			US-PGPUB;	]
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
_	326	(rotational same angle same detection) and maximum and	USPAT;	2004/08/27 14:34
	520	minimum and average	US-PGPUB;	
		Thin in and average	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	61	((rotational same angle same detection) and maximum and	USPAT;	2004/08/27 15:21
		minimum and average) and offset and gain	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
_	2	6097183.pn.	USPAT;	2004/08/27 14:22
	_	0037 203.pm	US-PGPUB;	2001/00/27 11:22
			EPO; JPO;	
	1			
			DERWENT;	
[		<b>,</b> , , , , , , , , , , , , , , , , , ,	IBM_TDB	
-	33	(rotational same angle same detection) and maximum and	USPAT;	2004/08/27 14:37
		minimum and average and sine and cosine	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
1_	5	73/862.331.ccls. and maximum and minimum and average	USPAT;	2004/08/27 14:47
		7.57002.351.ccis. and maximam and minimam and average	US-PGPUB;	200 1/00/27 11.17
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	4	73/862.326.ccls. and maximum and minimum and average	USPAT;	2004/08/27 14:48
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
_	2	5912638.pn.	USPAT;	2004/08/27 15:23
	-	3312330.pm.	US-PGPUB;	200 1/00/27 13:23
1				
ļ			EPO; JPO;	
			DERWENT;	
			IBM_TDB	0004/00/0= :=
-	2	4529922.pn.	USPAT;	2004/08/27 15:48
			US-PGPUB;	]
			EPO; JPO;	}
			DERWENT;	
1			IBM_TDB	1
1 -	9055	resolver	USPAT;	2004/08/27 15:48
		<del>-</del> -	US-PGPUB;	221., 22, 27.10
			EPO; JPO;	
			DERWENT;	
1			IBM_TDB	2004/00/27 17 15
-	1470	resolver and average	USPAT;	2004/08/27 15:48
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
1			IBM_TDB	
-	338	(resolver and average) and offset and gain	USPAT;	2004/08/27 15:48
		1 10001101 and arelage) and onset and gain	US-PGPUB;	230 1/00/27 13.40
			EPO; JPO;	
1			DERWENT;	
			IBM_TDB	L

-	302	((resolver and average) and offset and gain) and (maximum or minimum)	USPAT; US-PGPUB;	2004/08/27 15:49
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
·-	223	((resolver and average) and offset and gain) and (maximum	USPAT;	2004/08/27 16:37
		and minimum)	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	3	702/87.ccls. and resolver	USPAT;	2004/08/30 12:28
			US-PGPUB;	
1			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	10	702/87.ccls. and rotational\$4	USPAT;	2004/08/30 12:38
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
	_	702/07	IBM_TDB	2004/00/20 42 22
-	0	702/87.ccls. and (rotational adj measuring adj device)	USPAT;	2004/08/30 12:39
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
	١ ,	702/07 cele and untational and apple and appear	IBM_TDB	2004/00/20 42-50
] -	4	702/87.ccls. and rotational and angle and sensor	USPAT;	2004/08/30 12:50
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
	9079	resolver or (rotational near angle near sensor) and offset	IBM_TDB USPAT;	2004/08/30 12:53
-	9079	and gain	US-PGPUB;	2007/00/30 12.33
1	İ	and gain	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
_	1763	(resolver or (rotational near angle near sensor) and offset	USPAT;	2004/08/30 12:53
	1703	and gain) and maximum and minimum	US-PGPUB;	200 1,00,00 12:00
		ganif and manning and mining	EPO; JPO;	
1	1		DERWENT;	
			IBM_TDB	
_	329	((resolver or (rotational near angle near sensor) and offset	USPAT;	2004/08/30 12:57
		and gain) and maximum and minimum) and sine and cosine	US-PGPUB;	
		,	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	2	"20020124663"	USPAT;	2004/08/30 16:30
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	9107	resolver	USPAT;	2004/09/16 12:57
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	664	resolver and offset and gain	USPAT;	2004/09/16 12:57
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
	L		IBM_TDB	<u></u>

	45053	/ and a sed offert and arts) and size as arrive	LICDAT	2004/00/46 12:57
-	45957	(resolver and offset and gain) and sine or cosine	USPAT;	2004/09/16 12:57
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	249	(resolver and offset and gain) and sine	USPAT;	2004/09/16 12:58
		(	US-PGPUB;	
			EPO; JPO;	
1			DERWENT;	
			IBM_TDB	
-	197	(resolver and offset and gain) and cosine	USPAT;	2004/09/16 12:58
			US-PGPUB;	
l			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
_	5	(brushless near resolver) and gain and offset	USPAT;	2004/09/17 12:54
		(brasiless fiear resolver) and gain and onsec	US-PGPUB;	200 1/05/17 12.51
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	334	(resolver and gain and offset) and correction	USPAT;	2004/09/17 12:53
			US-PGPUB;	
1			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
	550	(votational poar angle) and gain and offeet		2004/09/17 12:55
-	550	(rotational near angle) and gain and offset	USPAT;	2004/03/17 12:55
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	321	((rotational near angle) and gain and offset) and correction	USPAT;	2004/09/17 14:35
		(	US-PGPUB;	, ,
			EPO; JPO;	
			DERWENT;	
	4.0	and all the second of the seco	IBM_TDB	2004/00/47 45:45
-	16	resolver and (differential near gain) and offset	USPAT;	2004/09/17 15:15
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
_	3	341/112.ccls. and differential and gain and offset	USPAT;	2004/09/17 16:21
		,	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
	3.5	244 (442 colo and recolumn	IBM_TDB	2004/00/47 46:44
-	31	341/112.ccls. and resolver	USPAT;	2004/09/17 16:41
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	128	341/116.ccls. and resolver	USPAT;	2004/09/17 17:01
		, =, =	US-PGPUB;	
	1		EPO; JPO;	
	1			
	1		DERWENT;	
			IBM_TDB	2004/00/15 15 55
-	134	resolver and error and correction and average and	USPAT;	2004/09/17 17:02
		differential and max and min	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
L	·	I		·

-	174	resolver and sine and cosine and offset and gain	USPAT;	2004/09/22 15:30
			US-PGPUB;	
İ			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	2	3974498.pn.	USPAT;	2004/09/30 10:52
	i	•	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	